



International Atomic Energy Agency

**An open source energy planning approach:
SOFT-MESSAGE**

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Outline

- **Objective: Component driven free evolvable optimization model**
- **View of some of the components**
 - **Interface, envelope, results viewer, model code etc.**
- **Basic equations**
- **Simple application**
- **Conclusions**

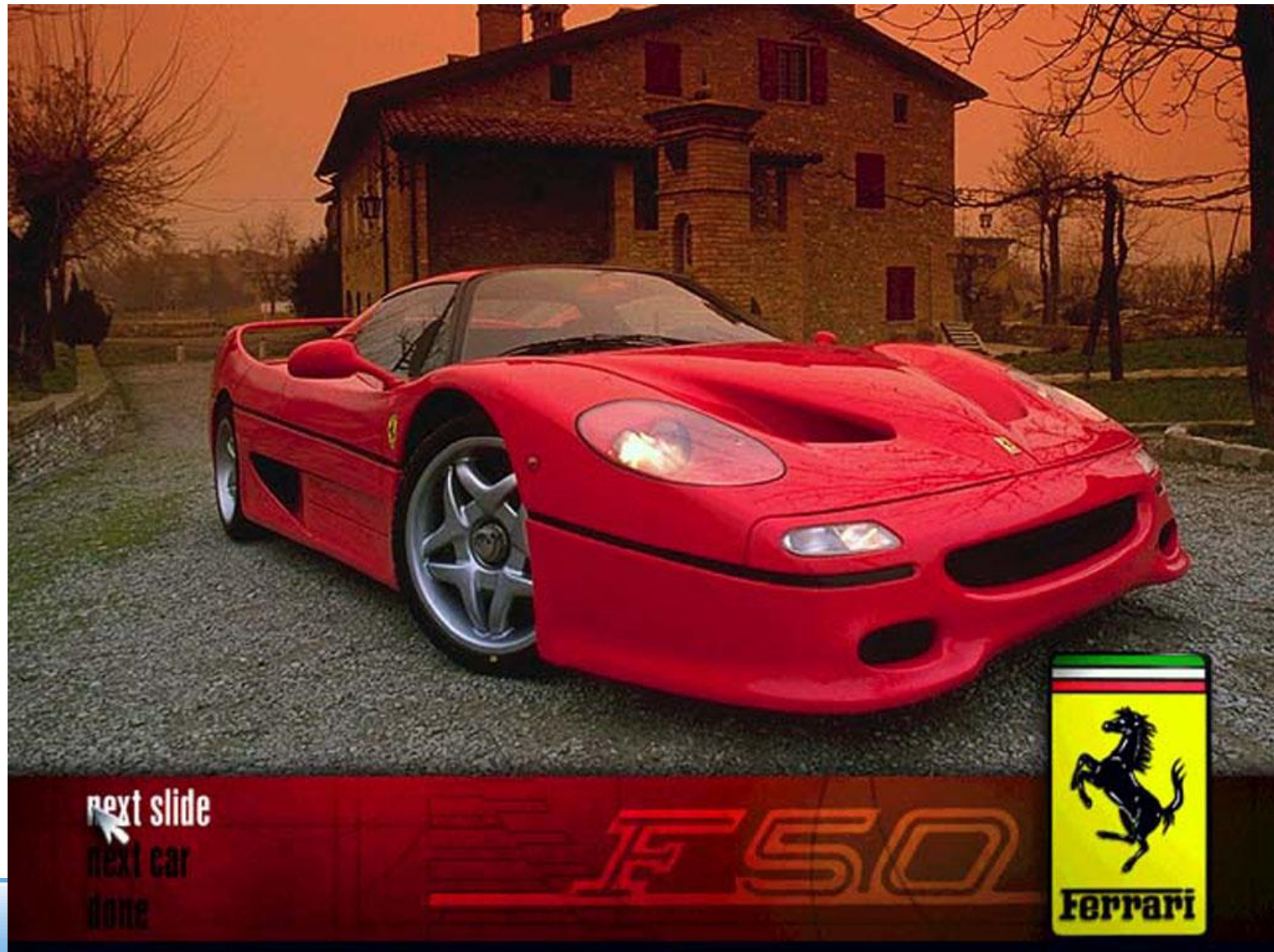


Selected objectives

- **Simple Open Flexible Transparent**
- **MESSAGE** (like MARKAL, TIMES, EFOM etc) is part of the Hefele-Manne family of models (limited but powerful)
- Reduce the barriers for uptake and basic capacity in the use of optimization models
 - For application (limited set of national medium term modeling)
 - For development (very easy access to all equations)
- Free and unrestricted distribution (all components)
- Should increase the need and use of more powerful approaches
- Improve the power of simple but popular approaches
- As development is open, evolution can be sustainable
- (Target is a limited set of medium term applications)



What we would like to see



What I am going to show you..

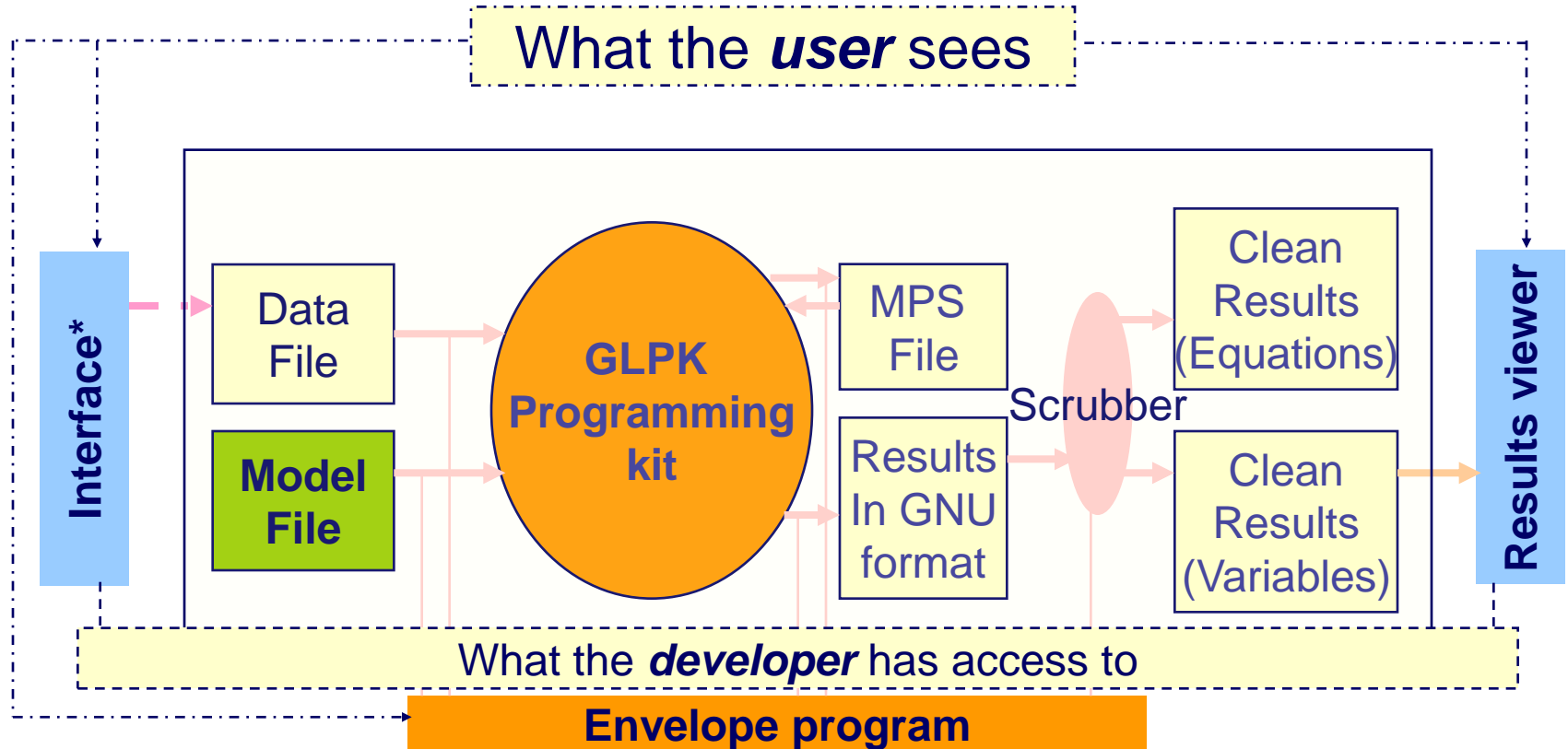


Component driven

- **Components that do not “lock us in”**
- **All aspects are “open” many service providers / programmers / enthusiasts**
- **Components are (as) independent (as possible)**
- **Can be changed, improved, replaced**
- **Components so far....**



Components



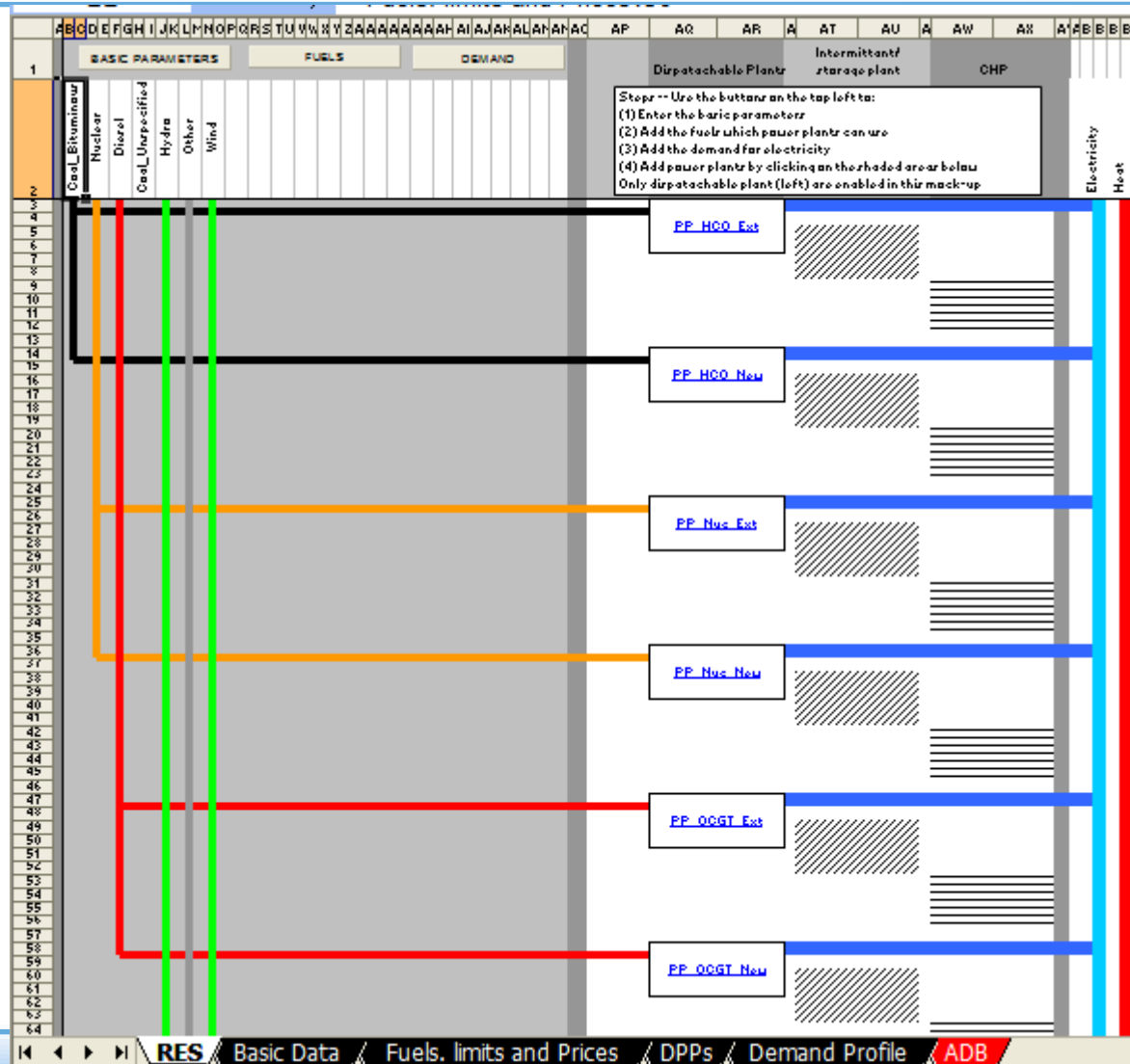
* Interface is ONLY for testing. It is also independent – could use LEAP – could use more symbolic interface – RES type interface.



Functional Mock-up interface

8

(To be scrapped soon. It was compiled to help testing. Again, the move is to make this as independent from specific implementation model implementation. We can also focus on simple intuitive interfaces. Could theoretically use the same model with a different interface: LEAP / ANSWER / VEDA etc)



Envelope Program

(Written in Java this picks up the Model file and Data file and then submits the run. The data is then cleaned for viewing / analysis)

The screenshot displays the 'Envelope' application window. It features a title bar with the name 'Envelope' and standard window controls. Below the title bar, there is a text field containing the file paths: 'Model File: MODEL_File_I EW_2008.txt' and 'Data File: DATA_File_I EW_2008.txt'. At the bottom of the window, there are four buttons: 'Model select', 'Data select', 'SOLVE', and 'SORT'. Overlaid on top of the Envelope window is a smaller window titled 'Shortcut to run_glpk_mod'. This window contains a list of commands being executed, such as 'Generating EQ_Const1...', 'Generating EQ_Const2...', and 'Generating EQ_DiscOperatingCosts...'. It also displays the results of the GLPK solver, including the number of rows and columns for the original and presolved LPs, and the objective value and infeasibility for several iterations.

```

C:\ Shortcut to run_glpk_mod
Generating EQ_Const1...
Generating EQ_Const2...
nt...
stment...
ar...
arAnl...
..
Generating EQ_DiscOperatingCosts...
Generating EQ_TotalCost...
Generating EQ_TotalAnnMaxCapacity...
Generating EQ_TotalAnnMinCapacity...
Generating RM_TechIncluded...
Generating RM_FuelIncluded...
Generating RM_Constraint...
Generating EmissionProduction1...
Generating EmissionProduction2...
Generating EmissionProduction3...
Generating EmissionsPenalty1...
Generating EmissionsPenalty2...
Model has been successfully generated
lpx_write_prob: writing problem data to 'Mtrx.txt'...
lpx_simplex: original LP has 99601 rows, 104430 columns, 271899 non-zero
lpx_simplex: presolved LP has 43540 rows, 50450 columns, 137386 non-zero
lpx_adv_basis: size of triangular part = 42970
200:  objval = 8.219554171e+006   infeas = 9.207843072e-001 (570)
400:  objval = 8.448518760e+006   infeas = 9.207838404e-001 (570)
600:  objval = 8.448518760e+006   infeas = 9.207838404e-001 (570)
800:  objval = 8.448518760e+006   infeas = 9.207838404e-001 (570)
1000: objval = 8.448518760e+006   infeas = 9.207838404e-001 (570)
  
```



Results viewer

(Written in Java. Excel breaks down when results sets are large. Again, this utility is completely independent of the interface, model file, data file etc.)

Display result data file

Click on the Data File button to choose the data to be shown on the table.
Click on the table headers to activate sorting

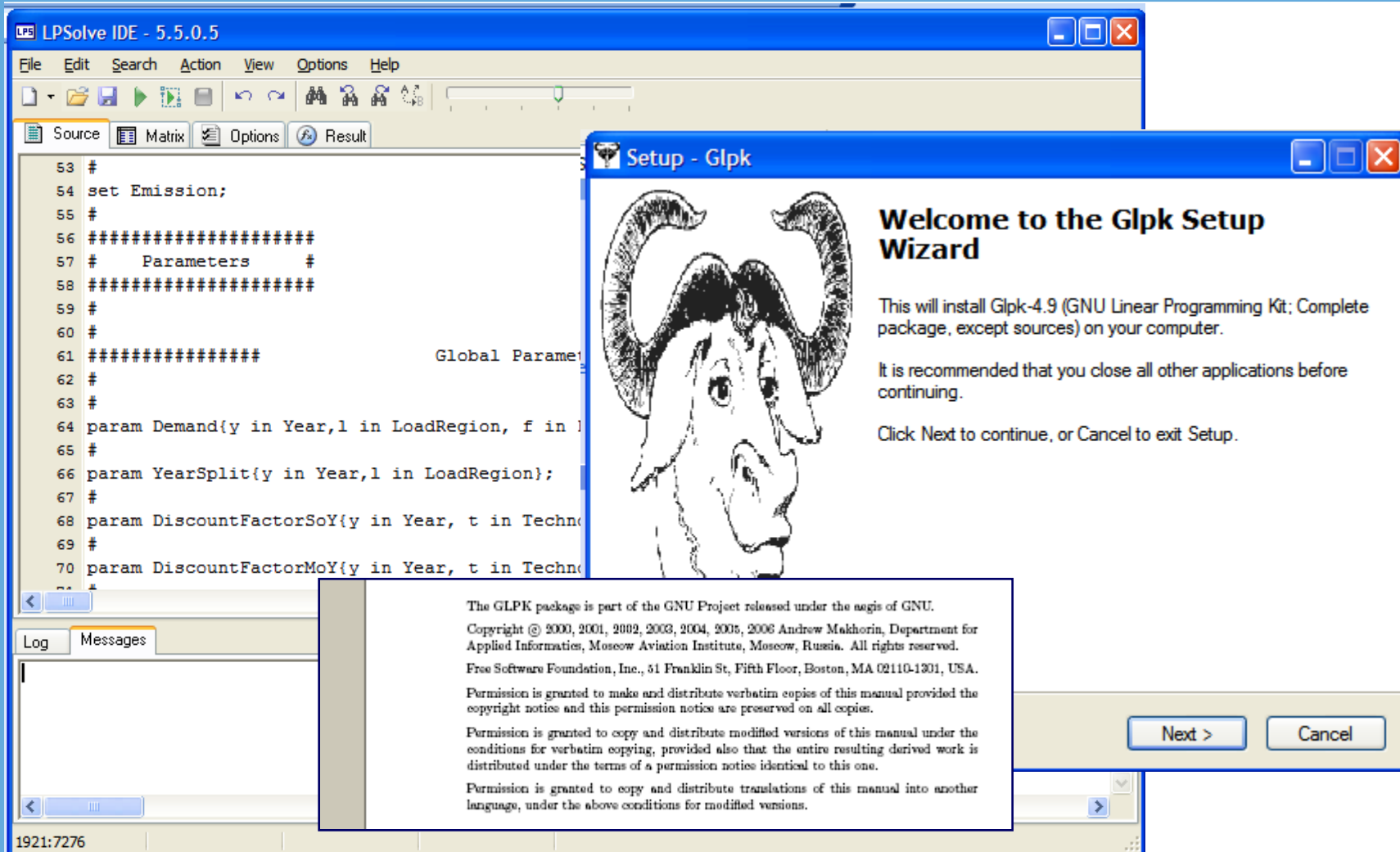
Data select

ID	Variable...	Year	ID2	ID3	ID4	St	Activity	Lowe...	Marginal	eps
	TotCapAr			PP_HCO_Ext						
19209	TotCap...	My2005	none	PP_HCO_Ext	none	B	35218	0	n/a	n/a
19229	TotCap...	My2006	none	PP_HCO_Ext	none	B	35218	0	n/a	n/a
19249	TotCap...	My2007	none	PP_HCO_Ext	none	B	35218	0	n/a	n/a
19269	TotCap...	My2008	none	PP_HCO_Ext	none	B	35218	0	n/a	n/a
19289	TotCap...	My2009	none	PP_HCO_Ext	none	B	35218	0	n/a	n/a
19309	TotCap...	My2010	none	PP_HCO_Ext	none	B	35218	0	n/a	n/a
19329	TotCap...	My2011	none	PP_HCO_Ext	none	B	35218	0	n/a	n/a
19349	TotCap...	My2012	none	PP_HCO_Ext	none	B	35218	0	n/a	n/a
19369	TotCap...	My2013	none	PP_HCO_Ext	none	B	35218	0	n/a	n/a
19389	TotCap...	My2014	none	PP_HCO_Ext	none	B	35218	0	n/a	n/a
19409	TotCap...	My2015	none	PP_HCO_Ext	none	B	35218	0	n/a	n/a
19429	TotCap...	My2016	none	PP_HCO_Ext	none	B	34543	0	n/a	n/a
19449	TotCap...	My2017	none	PP_HCO_Ext	none	B	34543	0	n/a	n/a
19469	TotCap...	My2018	none	PP_HCO_Ext	none	B	34543	0	n/a	n/a
19489	TotCap...	My2019	none	PP_HCO_Ext	none	B	34543	0	n/a	n/a
19509	TotCap...	My2020	none	PP_HCO_Ext	none	B	34543	0	n/a	n/a
19529	TotCap...	My2021	none	PP_HCO_Ext	none	B	31868	0	n/a	n/a
19549	TotCap...	My2022	none	PP_HCO_Ext	none	B	29768	0	n/a	n/a
19569	TotCap...	My2023	none	PP_HCO_Ext	none	B	29768	0	n/a	n/a
19589	TotCap...	My2024	none	PP_HCO_Ext	none	B	29768	0	n/a	n/a
19609	TotCap...	My2025	none	PP_HCO_Ext	none	B	29768	0	n/a	n/a
19629	TotCap...	My2026	none	PP_HCO_Ext	none	B	29768	0	n/a	n/a



GLPK Programming Kit

(A freeware subset of the AMPL mathematical programming language. Pictured is a development kit (IDE Solve by Henri Gourvest), part of the manual and the Glpk Setup)





```

param EmissionsPenalty{y in Year, e in Emission};
#
#
#####
# Model Variables #
#####
#
##### Capacity Variables #####
#
var NewCap{y in Year, t in Technology} := 0;
var NewCapVDim{v in Vintage, t in Technology};
var NewCapStructure{y in Year, v in Vintage, t in Technology} := 0;
var TotCapAnn{y in Year, t in Technology} := 0;
#
##### Activity Variables #####
#
var Activity1{y in Year, l in LoadRegion, t in Technology} := 0;
var Activity2{y in Year, l in LoadRegion, t in Technology} := 0;
var TotalActivity{y in Year, l in LoadRegion, t in Technology};
var Production1{y in Year, l in LoadRegion, f in Fuel};
var Production2{y in Year, l in LoadRegion, f in Fuel};
var TotalProduction{y in Year, l in LoadRegion, f in Fuel};
var Consumption1{y in Year, l in LoadRegion, f in Fuel};
var Consumption2{y in Year, l in LoadRegion, f in Fuel};
var TotalConsumption{y in Year, l in LoadRegion, f in Fuel};
#
##### Costing Variables #####
#
var CapitalInvestment{y in Year, t in Technology};
var DiscCapitalInvestment{y in Year, t in Technology};
var SalvageValue{y in Year, t in Technology};
var OperatingCost{y in Year, t in Technology};
var DiscOperatingCost{y in Year, t in Technology};
var AnnVarOpCost{y in Year, t in Technology};
var VarOpCost{y in Year, l in LoadRegion, t in Technology};
var TotalDiscCost{y in Year, t in Technology};
#
#
##### Storage Variables #####
#
# *****
#var NetStorageCharge{s in Storage, y in Year, l in LoadRegion};
#var StorageLevel{s in Storage, b in BoundryInstances};
#var StorageCharge{s in Storage, y in Year, l in LoadRegion};
#var StorageDischarge{s in Storage, y in Year, l in LoadRegion};
#var StorageOverflow{s in Storage, y in Year, l in LoadRegion} := 0;
#var RiverFlowAddedD{r in River, y in Year, l in LoadRegion};
#var RiverFlowAddedO{r in River, y in Year, l in LoadRegion};
#var RiverFlowAddedT{r in River, y in Year, l in LoadRegion};
#var RiverFlow{r in River, y in Year, l in LoadRegion};
#
# *****
#
##### Reserve Margin #####
#
#
var TotCapInRM{y in Year};

```

```

var DMDInRM{y in Year, l in LoadRegion};
#
#
##### Emissions #####
#
var AnnualTechEmission{y in Year, t in Technology, e in Emission};
var DiscAnnTechEmPen{y in Year, t in Technology, e in Emission};
var AnnualTechEmPenByEm{y in Year, t in Technology, e in Emission};
var AnnualTechEmPen{y in Year, t in Technology};
var AnnualEmissions{y in Year, e in Emission};
var EmissionsProd1{y in Year, t in Technology, e in Emission};
var EmissionsProd2{y in Year, t in Technology, e in Emission};
#
#####
# Objective Function #
#####
#
minimize cost: sum{y in Year, t in Technology} TotalDiscCost{y,t};
#
##### Constraints #####
#
# *****
#
#t.EQ_RiverFlowAddedD{r in River, y in Year, l in LoadRegion}: sum{s in Storage} FlowDump [r,s] *
StorageDischarge[s,y,l] = RiverFlowAddedD [r,y,l];
#t.EQ_RiverFlowAddedO{r in River, y in Year, l in LoadRegion}: sum{s in Storage} FlowDump [r,s] *
StorageOverflow[s,y,l] = RiverFlowAddedO [r,y,l];
#t.EQ_RiverFlowAddedT{r in River, y in Year, l in LoadRegion}: RiverFlowAddedD[r,y,l] +
RiverFlowAddedO [r,y,l] = RiverFlowAddedT [r,y,l];
#t.EQ_RiverFlow{r in River, y in Year, l in LoadRegion}: RiverInflow[r,y,l] - RiverOutflow[r,y,l] +
RiverFlowAddedT[r,y,l] = RiverFlow[r,y,l];
#t.EQ_StorageCharge{s in Storage, y in Year, l in LoadRegion}: sum{r in River} RiverFlow[r,y,l] *
RiverToStorage[r,s] = StorageCharge[s,y,l];
#t.EQ_NetStorageCharge{s in Storage, y in Year, l in LoadRegion}: NetStorageCharge[s,y,l] =
StorageCharge[s,y,l] - StorageOverflow[s,y,l] - StorageDischarge[s,y,l];
#t.EQ_St1{b in BoundryInstances, s in Storage}: sum{l in LoadRegion, y in Year}
NetStorageCharge[s,y,l]*StorageConstraint[y,l,b] = - StartLevel[s]*OneMatrixBoundryInstances[b] +
StorageLevel[s,b];
#t.EQ_St2{b in BoundryInstances, s in Storage}: StorageLevel[s,b] := 20;
#t.EQ_St3{b in BoundryInstances, s in Storage}: StorageLevel[s,b] := 500;
#t.EQ_StorageDischarge{s in Storage, y in Year, l in LoadRegion}: sum{t in Technology}
Activity1[y,l,t] * TechnologyToStorage[t,s] * YearSplit[y,l] = StorageDischarge[s,y,l];
#
#
# *****
#
# EQ_RiverFlow{y in Year, l in LoadRegion, r in River}: Inflow[y,l,r] - Outflow[y,l,r] + Dump[y,l,r];
# EQ_Dump{y in Year, l in LoadRegion, r in River}
#
#
#

```




```

##### Capacity sufficient for Activity #####
#
#
s.t. EQ_NewCapDimChange{y in Vintage, t in Technology}: sum{y in Year}
NewCap[y,t]*EDMatrix[y,v]=NewCapVDim[v,t];
s.t. EQ_Structure_Of_New_Investment{y in Year, v in Vintage, t in Technology}: NewCapVDim[v,t]*
VintageMatrix[y,v,t] = NewCapStructure[y,v,t];
s.t. EQ_TotCapAnn{y in Year, t in Technology}: sum{v in Vintage} NewCapStructure[y,v,t] =
TotCapAnn[y,t] - ResidualCapacity[y,t];
s.t. Constraint_Capacity{y in Year, l in LoadRegion, t in Technology}: TotCapAnn[y,t] *
CapacityFactor[y,t] * OneMatrixLR[l] == Activity1[y,l,t] + Activity2[y,l,t];

##### Activity includes "planned maintenance" #####
#
#
s.t. Tot_Activity{y in Year, t in Technology, l in LoadRegion}: Activity1[y,l,t] + Activity2[y,l,t] =
TotalActivity[y,l,t];
s.t. PlannedMaintenance{y in Year, t in Technology}: sum{l in LoadRegion}
TotalActivity[y,l,t]*YearSplit[y,l] <= TotCapAnn[y,t]*CapacityFactor[y,t]* AvailabilityFactor[y,t];
#
##### Production=Demand+Consumption #####
#
#
s.t. EQ_Prod1{y in Year, l in LoadRegion, f in Fuel}: sum{t in Technology}
Activity1[y,l,t]*OptActvtyRatio1[y,t,f] * OneMatrixLR[l] = Production1[y,l,f];
s.t. EQ_Prod2{y in Year, l in LoadRegion, f in Fuel}: sum{t in Technology}
Activity2[y,l,t]*OptActvtyRatio2[y,t,f] * OneMatrixLR[l] = Production2[y,l,f];
s.t. EQ_TotProd{y in Year, l in LoadRegion, f in Fuel}: Production1[y,l,f] + Production2[y,l,f] =
TotalProduction[y,l,f];
s.t. EQ_Con1{y in Year, l in LoadRegion, f in Fuel}: sum{t in Technology}
Activity1[y,l,t]*ImpActvtyRatio1[y,t,f] * OneMatrixLR[l] = Consumption1[y,l,f];
s.t. EQ_Con2{y in Year, l in LoadRegion, f in Fuel}: sum{t in Technology}
Activity2[y,l,t]*ImpActvtyRatio2[y,t,f] * OneMatrixLR[l] = Consumption2[y,l,f];
s.t. EQ_TotCons{y in Year, l in LoadRegion, f in Fuel}: Consumption1[y,l,f] + Consumption2[y,l,f] =
TotalConsumption[y,l,f];
s.t. EnBalance{y in Year, l in LoadRegion, f in Fuel}: TotalProduction[y,l,f] == Demand[y,l,f] +
TotalConsumption[y,l,f];
#
##### Capital Investment #####
#
#
s.t. EQ_CapitalInvestment{y in Year, t in Technology}: CapitalCost[y,t] * NewCap[y,t] =
CapitalInvestment[y,t];
s.t. EQ_DiscCapitalInvestment{y in Year, t in Technology}:
CapitalInvestment[y,t]*DiscountFactorSoY[y,t] = DiscCapitalInvestment[y,t];
#
##### Salvage Costs #####
#
#
s.t. EQ_SalvageValue{y in Year, t in Technology}: CapitalCost[y,t] * NewCap[y,t] * SalvageFactor[y,t] =
SalvageValue[y,t];
#
##### Operating Costs #####

```

```

#
#
s.t. EQ_OperatingCostsVar{y in Year, l in LoadRegion, t in Technology}:
Activity1[y,l,t]*VariableCost1[y,t]*YearSplit[y,l] + Activity2[y,l,t]*VariableCost2[y,t]*YearSplit[y,l]=
VarOpCost[y,l,t];
s.t. EQ_OperatingCostsVarAnn{y in Year, t in Technology}: sum{l in LoadRegion} VarOpCost[y,l,t] =
AnnVarOpCost[y,t];
s.t. EQ_OperatingCosts{y in Year, t in Technology}: TotCapAnn[y,t]*FixedCost[y,t]+AnnVarOpCost[y,t]
= OperatingCost[y,t];
s.t. EQ_DiscOperatingCosts{y in Year, t in Technology}: OperatingCost[y,t]*DiscountFactorMoY[y,t] =
DiscOperatingCost[y,t];
#
##### Total Discounted Costs #####
#
#
s.t. EQ_TotalCost{y in Year, t in Technology}: DiscOperatingCost[y,t]+DiscCapitalInvestment[y,t] -
SalvageValue[y,t]+ AnnualTechEmPen[y,t] =TotalDiscCost[y,t];
/* Could do the technology summation here!!!! */
#
##### Investment Constraints #####
#
#
s.t. EQ_TotalAnnMaxCapacity{y in Year, t in Technology}: TotCapAnn[y,t] <=
TotalAnnMaxCapacity[y,t];
s.t. EQ_TotalAnnMinCapacity{y in Year, t in Technology}: TotCapAnn[y,t] ==
TotalAnnMinCapacity[y,t];
#
#
##### Reserve Margin #####
#
#
s.t. RM_TechIncluded{y in Year, l in LoadRegion}: sum{t in Technology} TotCapAnn[y,t] *
RMTagTech[y,t] = TotCapinRM[y];
s.t. RM_FuelIncluded{y in Year, l in LoadRegion}: sum{f in Fuel} Demand[y,l,f] *
RMTagFuel[y,f] = DMDinRM[y];
s.t. RM_Constraint{y in Year, l in LoadRegion}:
DMDinRM[y] * RM[y]
<= TotCapinRM[y]*OneMatrixLR[l];
#
##### Emissions #####
#
#
s.t. EmissionProduction1{y in Year, t in Technology, e in Emission}: sum{l in LoadRegion}
EmissionActvtyRatio1[y,t,e]*Activity1[y,l,t]*YearSplit[y,l]=EmissionsProd1[y,t,e];
s.t. EmissionProduction2{y in Year, t in Technology, e in Emission}: sum{l in LoadRegion}
EmissionActvtyRatio2[y,t,e]*Activity2[y,l,t]*YearSplit[y,l]=EmissionsProd2[y,t,e];
s.t. EmissionProduction3{y in Year, t in Technology, e in Emission}: EmissionsProd1[y,t,e] +
EmissionsProd2[y,t,e] = AnnualTechEmission[y,t,e];
s.t. EmissionsPenalty1{y in Year, t in Technology, e in
Emission}: AnnualTechEmission[y,t,e]*EmissionsPenalty[y,e]=AnnualTechEmPenByEm[y,t,e];
s.t. EmissionsPenalty2{y in Year, t in Technology}: sum{e in Emission} AnnualTechEmPenByEm[y,t,e] =
AnnualTechEmPen[y,t];
s.t. EmissionsPenalty3{y in Year, t in Technology}: AnnualTechEmPen[y,t]*DiscountFactorMoY[y,t] =
DiscAnnTechEmPen[y,t];#

```



Basic equations (1)

Objective
function -
minimize:

$$\sum_y \sum_t TotalDiscCost_{y,t}$$

$$TotalDiscCost_{y,t} = DiscOperatingCost_{y,t} + DiscCapitalInvestment_{y,t} - SalvageValue_{y,t} + DiscEmissionsPenalty_{y,t}$$

$$DiscOperatingCost_{y,t} = OperatingCost_{y,t} * DiscountFactor_{y,t}$$

$$OperatingCost_{y,t} = TotCapAnn_{y,t} * FixedCost_{y,t} + \sum_l (Activity_{y,l,t} * VariableCost_{y,t} * YearSplit_{y,l})$$

$$DiscCapitalInvestment_{y,t} = CapitalCost_{y,t} * NewCap_{y,t} * DiscountFactor_{y,t}$$

$$Production_{y,l,f} \geq Demand_{y,l,f} + Use_{y,l,f}$$

Where :

$$Production_{y,l,f} = \sum_t (Activity_{y,l,t} * OtptActvtyRatio_{y,t,f} * YearSplit_{y,l})$$

$$Use_{y,l,f} = \sum_t Activity_{y,l,t} * InptActvtyRatio_{y,t,f} * YearSplit_{y,l}$$



Basic equations (2)

$$\sum_l (Activity_{y,l,t} * YearSplit_{y,l} * EmissionActvtyRatio_l) = EmissionsProd_{y,t,e}$$

$$EmissionsProd_{y,t,e} * EmissionsCost_{y,e} = EmissionsPenalty_{y,t,e}$$

$$\sum_e (EmissionsProd_{y,t,e} * EmissionsCost_{y,e}) = EmissionsPenalty_{y,t}$$

$$EmissionsPenalty_{t,y} * DiscountFactor_{t,y} = DiscEmissionsPenalty_{t,y}$$

$$(DMDinRM_{y,l,f} + Use_{y,l,f}) * (1 + RM_{y,f}) \leq TotCapinRM_{y,f}$$



A Case study: High fossil fuel price imports,¹⁷ a carbon tax and a RE target

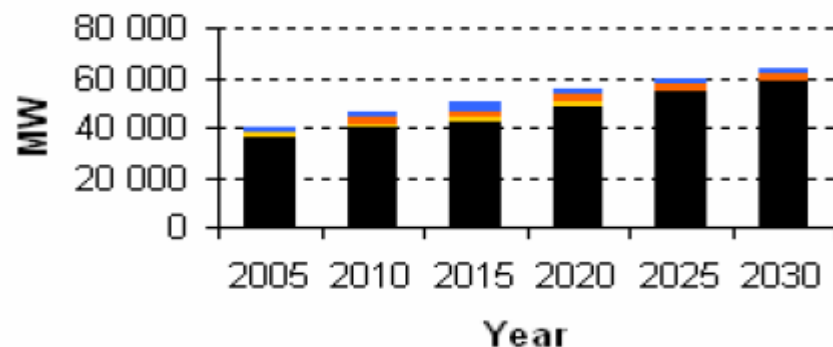
Repeated from Rogner et al WEC 2007

Security scenarios	Cases		
	Reference case	Renewable energy target case (RET)	
No security challenge			
High fossil fuel prices	Reference case under high fossil fuel prices	RET case under high fossil fuel prices	Optimal Response (OR) Case to high fossil fuel prices.
Carbon tax	Reference case under a carbon tax	RET case under a carbon tax	OR Scenario under a carbon tax.

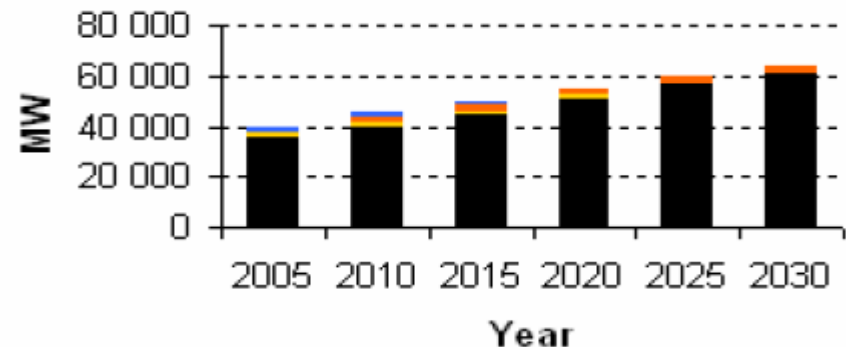


Case Study: Total installed capacity

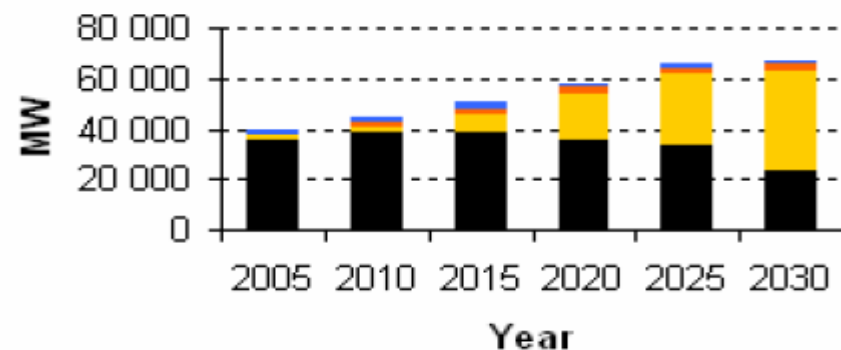
Reference Case



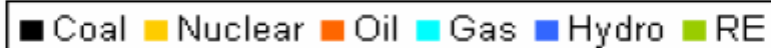
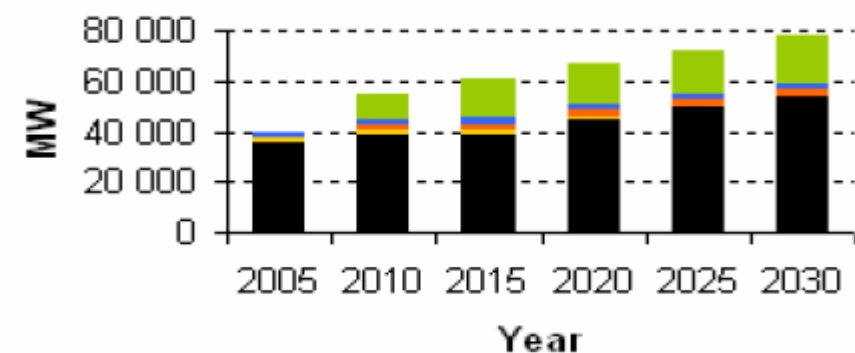
High Fossil Fuel Price Scenario - Optimal Response Case



Carbon Tax Scenario - Optimal Response Case

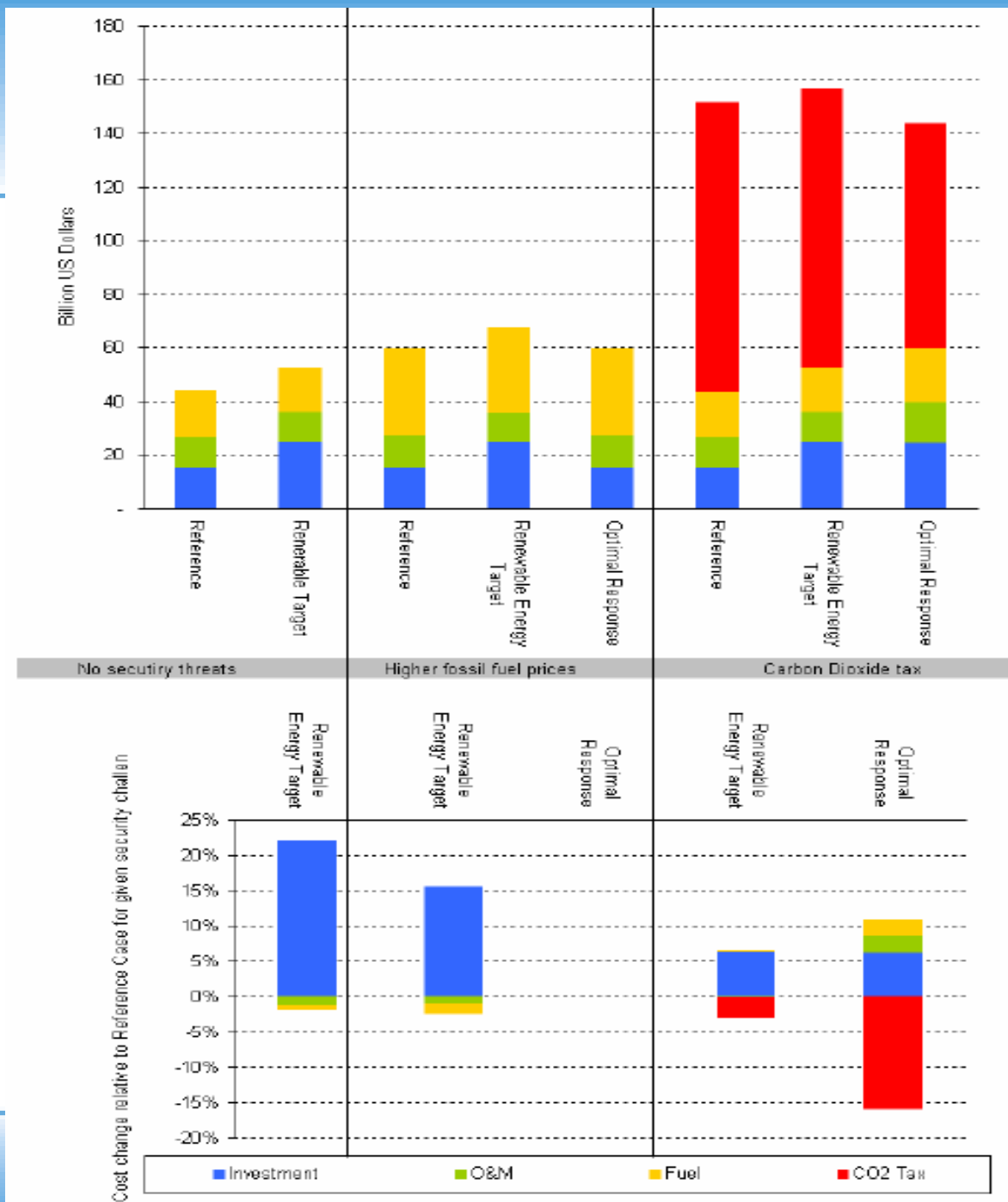


Renewable Energy Target Case



Case study:

- Total costs (top)
- Costs relative to Reference scenario
 - (under the same “security challenge”)



Conclusions

- **Developed a first free OS energy planning model**
- **Hope to reduce the barriers to entry and increase modeling capacity at two levels:**
 - Users
 - Developers
- **Simplified**
 - “Power modelers” will still need “power tools”, solvers etc.
 - Not aimed at long term modelling (rather medium term annual granulation)
 - Applicable for a large set of “first order” country applications
- **Will continue development of components**
 - Stand alone
 - Testing and deployment
 - Integration with other tools e.g. LEAP
 - This is an evolving tool (and a first iteration is presented here)
- **Allows a basis for further development and experiments**
 - Test new approaches on a simple small scale
 - Develop skills in research, university and other contexts
 - Come up with better representations than those given here

